

# Three Inference Questions

(1)

Decision Theory - what should I do after observing data?

Belief Theory - what do I believe after observing data?

Evidential Analysis - what do data say about hypotheses?

⇒ Evidence is reflected in how much prob is changed by data  
not what its magnitude is (or was)

Law of Likelihood - If  $H_1 \Rightarrow X \sim P(X|H_1)$  and  $H_2 \Rightarrow X \sim P(X|H_2)$   
Observation  $X=x$  is evidence supporting  $H_1$  over  $H_2$  iff

$$P(x|H_1) > P(x|H_2) \Leftrightarrow \frac{P(x|H_1)}{P(x|H_2)} > 1$$

Likelihood ratio  $\frac{P(x|H_1)}{P(x|H_2)}$  measures strength of evidence for  $H_1$  over  $H_2$

LR between 1+8 - weak evidence	∞-definitive evidence	$\frac{P(\text{data} H_1)}{P(\text{data} H_2)}$
between 8+32 - moderate evidence		
over 32 - strong evidence		

Law of Improbability says if prob of observing  $X=x$  under  $H_0$  is low, then  
 $X=x$  is evidence against  $H_0$

! specifies - lacks relation to second hypothesis

Likelihood Function  $L(\theta|x) \propto f(x|\theta)$

A model is identifiable if unique parameters imply unique density functions

Kullback-Leibler Divergence - measure of disparity between two distributions

$$kLD(g,f) = E_g \left[ \log \frac{g(x)}{f(x)} \right] \geq 0$$

Hellinger Distance provides a lower bound for kLD

$$kLD(g,f) \geq 2[H(f,g)]^2$$

$H_f: X \sim f(x)$      $H_g: X \sim g(x)$  observe  $x_1, \dots, x_n$  iid f or g

(2)

$$LR_n = \frac{\prod_{i=1}^n f(x_i)}{\prod_{i=1}^n g(x_i)}$$

How often is LR big when we want it to be small?

$$P_g(LR_n > k) \leq \frac{E_g[LR_n]}{k} = \frac{1}{k} \quad \text{by Markov's}$$

### Universal Bound

Universal Bound also holds sequentially

Let  $X_1, \dots, X_n \stackrel{iid}{\sim} g(x)$      $H_g: X \sim g(x)$      $H_f: X \sim f(x)$      $LR_n = \frac{\prod f(x_i)}{\prod g(x_i)}$

As evidence accumulates  $LR_n \rightarrow 0$

if  $X_1, \dots, X_n \stackrel{iid}{\sim} f(x)$   $LR_n \rightarrow \infty$

Likelihood Ratio converges to truth asymptotically

Asymptotic Behavior of LR drives posterior convergence

### Maximum Likelihood estimator (MLE)

1. get Likelihood  $L$
2. get log-likelihood  $\ell = \log L$
3. Take derivative  $\frac{\partial \ell}{\partial \theta} = \ell'$  (score function)
4. set score function = 0
5. solve for parameter

- MLE may not be unique
- MLE may not have analytical solution
- MLEs are often biased
- MLEs are consistent (if conditions met)
  - Identifiable
  - Continuity
  - Compactness
  - Dominance

### Invariance of MLE

Let  $\hat{\theta}$  be MLE of  $\theta$  and  $\gamma(\theta)$  some one-to-one function of  $\theta$   
 then  $\gamma(\hat{\theta})$  is the MLE of  $\gamma(\theta)$

- MLE minimizes KLD between truth and model
- MLE is asymptotically efficient (obeys CR LB) + asymptotically normal
- MLE is function of the MSS, but not necessarily the MSS itself

## Properties of Estimators

$$\text{Bias } E[\hat{\theta} - \theta] = b(\hat{\theta})$$

$$\text{Variance } E[(\hat{\theta} - E(\hat{\theta}))^2] = \text{Var}(\hat{\theta})$$

$$\text{Mean Square Error (MSE)} \quad E[(\hat{\theta} - \theta)^2] = \text{MSE}(\hat{\theta}) = \text{Var}(\hat{\theta}) + b^2(\hat{\theta})$$

Consistency  $\hat{\theta} \rightarrow \theta$  as  $n \rightarrow \infty$

## Bayes Estimators

for joint  $f(\underline{x}|\theta)$  and prior  $f(\theta)$  posterior is

$$f(\theta|\underline{x}) = \frac{f(\underline{x}|\theta)f(\theta)}{\int_{\theta} f(\underline{x}|\theta)f(\theta) d\theta}$$

posterior mean will shrink the sample mean toward prior mean

Bayes Estimators trade some bias for reduction in variance

## Continuous Mapping Theorem (CMT)

Let  $\{\underline{X}_n\}$  be elements in space  $S$ . Let  $g$  be function s.t.  $g: S \rightarrow S'$  with discontinuity points  $D_g$  s.t.  $P(\underline{X} \in D_g) = 0$ . Then

$$\underline{X}_n \xrightarrow{d} \underline{X} \Rightarrow g(\underline{X}_n) \xrightarrow{d} g(\underline{X})$$

$$\underline{X}_n \xrightarrow{P} \underline{X} \Rightarrow g(\underline{X}_n) \xrightarrow{P} g(\underline{X})$$

$$\underline{X}_n \xrightarrow{\text{a.s.}} \underline{X} \Rightarrow g(\underline{X}_n) \xrightarrow{\text{a.s.}} g(\underline{X})$$

by CMT  $s_n \rightarrow \sigma$ , but  $E[s_n] = E[h(s_n)] < hE[s_n^2] = h(\sigma^2) = \sigma^2$  so biased.  
consistent estimators can be biased. Bias converges to 0 (shrinks with sample size)

## Inconsistent MLE Examples

D. Basu - discontinuous Likelihood Function

Neyman-Scott problem - infinite nuisance parameters  
 (add parameters as increase  $n$ )

## Score Functions

derivative of log-likelihood

$$S_i = \frac{d \ell(\theta; x_i)}{d \theta} = \frac{d \log f(x_i; \theta)}{d \theta}$$

$$S_n = \sum_{i=1}^n S_i$$

1. Score function gives MLE

2. Score function is unbiased estimator of  $\theta$   $E[S_n] = 0$   
If model wrong, get biased estimate

$$\sqrt{n}(S_n) \xrightarrow{d} N(0, \text{Var}(S_i)) = N(0, I(\theta))$$

$$\frac{\sqrt{n}(S_n - 0)}{\sqrt{\text{Var}(S_i)}} \xrightarrow{d} N(0, 1)$$

$$\text{Var}(S_i) = E[S_i^2] - (E[S_i])^2 = E[S_i^2] = E\left[\left(\frac{d \log f(x_i)}{d \theta}\right)^2\right] = I(\theta)$$

Fisher Information is the variance of the score function

$$I_n(\theta) = \text{Var}(\sum S_i) = n I(\theta) \quad \begin{matrix} \text{estimate } I_n(\hat{\theta}) \\ \text{of information} \end{matrix}$$

## Bartlett's Identity

$$\text{Var}(S_i) = E[S_i^2] = -E[S_i'] \quad \text{if the model is correct}$$

## Asymptotic Normality of MLE

Taylor expansion  $\ell'(\hat{\theta})$  around  $\ell'_n(\theta)$   $\hat{\theta} - \theta \approx \frac{\ell'(\theta)}{-\ell''_n(\theta)}$  score function  
information

$$\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{d} N(0, \frac{1}{I(\theta)})$$

$$\sqrt{n} I(\hat{\theta})(\hat{\theta} - \theta) \xrightarrow{d} N(0, 1)$$

## Robustness

(5)

What happens when working model is not the true model?

let  $g$  be true model and  $f$  be working model

MLE,  $\hat{\theta}_n$  converges to  $\theta_g$ , the value of  $\theta$  which minimizes the KLD (disparity) between  $f(x, \theta)$  and  $g(x)$

$$\hat{\theta}_n \rightarrow \arg\min E_g \left[ \log \frac{g(x)}{f(x)} \right] = \theta_g$$

Object of Inference,  $\theta_g$

$$\frac{\partial E_g [\log f(x)]}{\partial \theta} := 0 \quad \text{solve for } \theta_g$$

does  $\theta_g = E_g[x]$ ?

If object of inference is not object of interest, find different working model

If yes, consider variance and efficiency

under model failure distribution of MLE is

$$\sqrt{n}(\hat{\theta} - \theta_g) \xrightarrow{d} N(0, \frac{b}{a^2}) \quad b = E[(S_i)^2] \quad a = -E[S_i]$$

estimate  $b$  and  $a$  with

$$\hat{b} = \frac{1}{n} \sum (S_i|_{\theta=\hat{\theta}})^2 \quad \hat{a} = \frac{-1}{n} \sum S_i|_{\theta=\hat{\theta}} \quad \text{to get sandwich estimator } \frac{\hat{b}}{\hat{a}^2}$$

ratio  $\frac{\hat{a}}{\hat{b}}$  gauges degree to which Bartlett's 2nd identity fails ( $= \frac{\text{model used var}}{\text{sample var}}$ )

Robust adjusted likelihood

$$L_R(\theta) = L(\theta)^{\hat{a}/\hat{b}}$$

under model failure LR for false alternative over  $\theta_g$   $\frac{L_n(\theta)}{L_n(\theta_g)} \rightarrow 0$  as  $n \rightarrow \infty$

$$P\left(\frac{L(\theta_n)}{L(\theta_0)} > k\right) = \Phi\left[\frac{-\log k}{c^*} - \frac{c^*}{2}\right] \quad \text{for correct model LR} + \text{robust adjusted LR}$$

## Estimating Equations

Take equation that is function of the data and unknown parameter and solve for unknown parameter

estimating equation unbiased if  $E[g(\underline{X}; \theta)] = 0$

standardized estimating equation

$$g_s(\underline{X}; \theta) = \frac{g(\underline{X}; \theta)}{E\left[\frac{\partial g(\underline{X}; \theta)}{\partial \theta}\right]}$$

optimal estimating equation has smallest variance in its class

$$\text{Var}[g_s(\underline{X}; \theta)] = \frac{E[g_s^2]}{\left(E\left[\frac{\partial g}{\partial \theta}\right]\right)^2}$$

true score function is an optimal estimating equation

method of moments

$$E[X_i] = \mu \quad \frac{1}{n} \sum X_i - \mu = 0, \text{ solve for } \mu$$

$$\text{Var}[X_i] = \sigma^2 \quad \frac{1}{n} \sum (X_i - \mu)^2 - \sigma^2 = 0, \text{ solve for } \sigma^2$$

$$\text{var}(g_s(\underline{X}; \theta)) \geq \frac{1}{I_n(\theta)}$$

Lower bound is achieved if function can be written as

$$g(\underline{X}; \theta) = a(\theta) [T(\underline{X}) - E[T(\underline{X})]] = a(\theta) [T(\underline{X}) - h(\theta)]$$

function of data alone      function of parameter alone

Cramer-Rao Lower Bound (CRLB) is minimum variance for any unbiased estimator of  $h(\theta)$

$$\text{Var}(T(\underline{X})) \geq \frac{[h'(\theta)]^2}{I_n(\theta)}$$

(7)

## Sufficiency

How much can sample be compressed without losing any information?  
What is smallest amount of info needed to write down likelihood function

Definition: A statistic  $T(\underline{X})$  is a sufficient statistic for  $F$  if the conditional distribution of  $\underline{X}$  given  $T(\underline{X})$  is same for all distributions in  $F$ .

$T(\underline{X})$  sufficient if  $P(\underline{X} \in A | T(\underline{X}) = t; \theta)$  is same for all  $\theta \in \Theta$

$T(\underline{X})$  is function of data that has all information about  $\theta$

Factorization Theorem  $T(\underline{X})$  is sufficient for  $\theta$  if + only if

$$f_{\underline{X}}(\underline{x}; \theta) = g(T(\underline{x}); \theta) h(\underline{x})$$

where  $h(\underline{x})$  does not depend on  $\theta$

## Minimal sufficiency

- sufficiency is specific to model. If  $T(\underline{X})$  sufficient for  $F$ , sufficient for  $F' \subseteq F$
- if  $T(\underline{X}) = w(S(\underline{X}))$  and  $T(\underline{X})$  sufficient,  $S(\underline{X})$  also sufficient
- any 1-to-1 function of a sufficient stat is also a sufficient stat

A sufficient statistic is minimally sufficient if it is a function of every other sufficient stat

The likelihood function is itself the MSS

Find MSS

$$\text{ratio } \frac{f(\underline{x}; \theta)}{f(\underline{y}; \theta)} = h(\underline{x}, \underline{y}) \quad \begin{matrix} \text{find stat that will make ratio free} \\ \text{of parameters} \end{matrix}$$

Rao-Blackwellization

Start with unbiased estimator  $\hat{\theta}$  and sufficient statistic  $T(\underline{x})$   
 make new estimator  $\tilde{\theta} = E[\hat{\theta}|T(\underline{x})]$

$$\text{Var}(\tilde{\theta}) \leq \text{Var}(\hat{\theta})$$

Ancillarity

A statistic is ancillary if it contains no information about  $\theta$

$S(\underline{x})$  is ancillary if its distribution doesn't depend on  $\theta$

Show  $f_s(S(\underline{x})|\theta)$  doesn't depend on  $\theta$

first order ancillary

$E[S(\underline{x})|\theta]$  doesn't depend on  $\theta$

$\Rightarrow$  MSS may not be independent of ancillary statistic  
 only happens when distribution is complete (Basu's Thm)

Summary

$$L(\theta; \underline{x}) = f(\underline{x}; \theta)$$

$$= g(t, a; \theta) h_1(x) \text{ by sufficiency [factorization thm]}$$

$$= g(t|a; \theta) h_2(a; \theta) h_1(x)$$

$$= g(t|a; \theta) h_2(a) h_1(x) \text{ by ancillary for } \theta$$

$$\propto g(t|a; \theta)$$

$$= g(t; \theta) \text{ if } T(\underline{x}) \perp A(\underline{x}) \text{ (family is complete)}$$

(9)

Completeness

let  $f(t|\theta)$  be pdf for statistic  $T(\underline{X})$ . family of  $f$  is complete if

$$E[g(t)] = 0 \quad \forall \theta \Rightarrow g(t) = 0 \quad \forall \theta$$

Basu's Thm if  $T(\underline{X})$  is complete + MSS, then  $T(\underline{X})$  is independent of every ancillary stat

Lemma if MSS exists, any CSS is also the MSS

Lehmann-Scheffe Thm if  $T(\underline{X})$  is CSS any stat  $h(T(\underline{X}))$  w/ finite variance is MVUE of  $E[h(T(\underline{X}))]$

condition on CSS to produce estimate w/ smallest variance of all unbiased estimators.

Check for completeness

1) exponential families are complete if the interior of the param space is nonempty

$$h(x) c(\theta) \exp\left[\sum_j t_j(x) w_j(\theta)\right]$$

$$T(\underline{X}) = \left( \sum_{i=1}^n T_1(X_i), \dots, \sum_{i=1}^n T_k(X_i) \right) \text{ is CSS}$$

2) use definition directly

find MVUE

start w/ unbiased estimator (try  $X_i$ )  
condition on CSS (Blackwellize)

## Conditionality, Sufficiency & Likelihood Principles

Conditionality principle - evidence about parameter of interest depends only on the observed data

⇒ Always condition on ancillary statistics

p-values & other probability calculations don't respect conditionality because they depend on sample space (ie. experiments that were not performed)

Sufficiency principle - sufficient statistic carries all the info about the parameter of interest.

⇒ Two data sets with same sufficient stat. should yield same evidence about parameter of interest

Likelihood Principle - the likelihood contains all the statistical evidence in the data

⇒ If two likelihoods are the same, the evidence should be the same

$$CP + SP \Rightarrow LP$$

### 3 Evidential Quantities

1) strength of evidence - LR

2) propensity for study to yield misleading evidence - reliability of study design

$$m_{is_0} = P(LR > k | H_0)$$

$$m_{is_1} = P(LR < k | H_1)$$

3) propensity for observed results to be misleading - reliability of data

$$P(H_0 | LR > k)$$

$$P(H_1 | LR < k)$$

CP & LP apply to evidence + observed data, not statistical properties of study design

Evidence & operating characteristics are NOT the same thing

## Interval Estimation

$X_1, \dots, X_n \sim N(\theta, \sigma^2)$ . Estimate  $\theta$  w/ MVUE or MLE  
 since  $\bar{X} \sim N(\theta, \frac{\sigma^2}{n})$   $\bar{X}$  will be close to  $\theta$

$$P(-1.96 \leq \frac{\bar{X} - \theta}{\sigma/\sqrt{n}} \leq 1.96) = 0.95$$

↑  
pivot (statistic whose dist. is  
free of unknown parameters)

Random interval  $P(\bar{X} - 1.96 \frac{\sigma}{\sqrt{n}} \leq \theta \leq \bar{X} + 1.96 \frac{\sigma}{\sqrt{n}}) = 0.95$

Fixed interval  $P(\theta - 1.96 \frac{\sigma}{\sqrt{n}} \leq \bar{X} \leq \theta + 1.96 \frac{\sigma}{\sqrt{n}}) = 0.95$

•  $100(1-\alpha)\%$  confidence region  $P(I(X))$  contains  $\theta$  ( $\theta$ ) =  $P_\theta(\theta \in I(x)) = 1-\alpha \quad \forall \theta \in \Theta$   
 confidence coefficient  $1-\alpha$  measures how often procedure captures  $\theta$

• Credible interval - Bayesian posterior dist  $P(\theta | \bar{x})$   
 $P(a(x) \leq \theta \leq b(x) | \bar{x} = \bar{x}) = 1-\alpha \quad [a(\bar{x}), b(\bar{x})]$  is  $1-\alpha$  credible int.

• support intervals - A  $1/k$  likelihood support interval is

$$\left\{ \theta : \frac{L(\theta)}{L(\hat{\theta})} \geq \frac{1}{k} \right\} = \left\{ \theta : \frac{L(\theta)}{U(\theta)} \leq k \right\} \quad \text{where } k > 1 \quad \text{and } \hat{\theta} \text{ is MLE for } \theta$$

### Criteria for intervals

1) Expected Lengths, for  $\bar{x} \pm 1.96 \frac{\sigma}{\sqrt{n}}$   $E[2 \cdot 1.96 \frac{\sigma}{\sqrt{n}}]$

Pratt Pm - expected length of  $c(x) = [L(x), U(x)]$  is sum(integral) of  
 prob. of false coverage over all false values of parameter

$$E_{\theta^*}(\text{length}(c(x))) = \int_{\theta \neq \theta^*} P(\theta \in c(x)) d\theta$$

2) Unbiasedness - Interval  $I(x)$  is unbiased if

$$P_\theta(I(x) \text{ contains } \theta') \leq 1-\alpha \quad \forall \theta' \neq \theta$$

where  $\theta'$  is a false value of  $\theta$

'More likely to contain true value than any false value'

3) Selectivity - Let  $I_1$  &  $I_2$  be two  $100(1-\alpha)\%$  CIs

$I_1$  is more selective than  $I_2$  if

$$P_\theta(\theta' \in I_1(x)) \leq P_\theta(\theta' \in I_2(x)) \quad \forall \theta' \neq \theta$$

" $I_1$  tends to exclude false values more often"

Common CIs

1.  $X_1, \dots, X_n \sim N(\mu, \sigma^2)$

$$\frac{\sqrt{n}(\bar{X}-\mu)}{\sigma} \sqrt{\frac{(n-1)S^2/\sigma^2}{n-1}} = \frac{Z}{\sqrt{S^2/\text{df}}} = \frac{\sqrt{n}(\bar{X}-\mu)}{S} \sim t_{n-1}$$

$$P(\bar{X} - t_{\alpha/2}^{n-1} \frac{S}{\sqrt{n}} \leq \mu \leq \bar{X} + t_{\alpha/2}^{n-1} \frac{S}{\sqrt{n}}) = 1-\alpha$$

pivot-dist. doesn't depend on  $\mu$  or  $\sigma^2$ 

2.  $X_1, \dots, X_n \sim N(\mu, \sigma^2) \quad Y_1, \dots, Y_m \sim N(\eta, \sigma^2) \quad X_i \perp Y_j$

$$\bar{X}_n - \bar{Y}_m \sim N(\mu - \eta, \sigma^2(\frac{1}{n} + \frac{1}{m}))$$

$$\frac{\bar{X} - \bar{Y} - (\mu - \eta)}{\sqrt{\sigma^2(\frac{1}{n} + \frac{1}{m})}} / \sqrt{\frac{(n-1)S_x^2}{\sigma^2} + \frac{(m-1)S_y^2}{\sigma^2}} = \frac{Z}{\sqrt{S_p^2}} = \frac{\bar{X} - \bar{Y} - (\mu - \eta)}{\sqrt{S_p^2(\frac{1}{n} + \frac{1}{m})}} \sim t_{n+m-2}$$

$$\bar{X} - \bar{Y} \pm t_{\alpha/2}^{n+m-2} \sqrt{S_p^2(\frac{1}{n} + \frac{1}{m})}$$
 is  $100(1-\alpha)\%$  CI for  $E[X] - E[Y]$ 

3.  $X_1, \dots, X_n \sim N(\mu, \sigma^2)$  CI for variance

$$\frac{(n-1)S^2}{\sigma^2} = \frac{\sum(X_i - \bar{X})^2}{\sigma^2} \sim \chi^2_{n-1} \quad P\left(\frac{(n-1)S^2}{a} \leq \sigma^2 \leq \frac{(n-1)S^2}{b}\right) \text{ is } 100(1-\alpha)\% \text{ CI for } \sigma^2$$

could choose  $a+b$  to get 1) equal tail areas 2) shortest interval 3)  $a=0$ , choose  $b$ Robust Large Sample Intervals

for  $\hat{\theta}$  MLE  $\sqrt{I_n(\theta)}(\hat{\theta} - \theta) \xrightarrow{d} N(0, 1)$

$$\hat{\theta} \pm z_{\alpha/2} (I(\hat{\theta}))^{-1/2}$$
 large sample  $100(1-\alpha)\%$  CI

$$\hat{\theta} \pm z_{\alpha/2} (I(\hat{\theta}))^{-1/2}$$
 approx. large sample  $100(1-\alpha)\%$  CI
also approx if replace  $I(\hat{\theta})$  with  $I_{\text{obs}}(\hat{\theta}) = -\sum \frac{\partial^2 \ell}{\partial \theta^2}$ 

neither are consistent oft of true info if working model fails

## Criteria for CI validity

1. Consistent estimator of parameter  $\hat{\theta} \rightarrow \theta$ 2. Asymptotic Normality  $\sqrt{I_n(\theta)}(\hat{\theta} - \theta) \xrightarrow{d} N(0, 1)$ 3. Consistent estimator of information  $I_n(\hat{\theta})/I_n(\theta) \rightarrow 1$ can make intervals robust by using  $S^2$  to estimate variance

$$P\left(\frac{\sqrt{n}(\hat{\theta} - \theta)}{\sqrt{S^2}} \sqrt{\frac{S^2}{S^2}} \leq z_{\alpha/2}\right) \rightarrow 1-\alpha$$

1st part  $N(0, 1)$  by CLT  
2nd part  $\rightarrow 1$  consistent

## Hypothesis Testing

Hyp. Test is choice between  $H_0$  &  $H_1$ , type I errors & type II errors used  
And critical region  $C$  controls type I errors

Neyman-Pearson Lemma if  $C$  is critical region such that for  $H_0$   $f(x; \theta_0)$   
 $H_1$   $f(x; \theta_1)$

$$1. \frac{f_1(x)}{f_0(x)} \geq k \quad \forall x \in C \quad k > 0$$

$$2. \frac{f_1(x)}{f_0(x)} < k \quad \forall x \in C^c$$

$$3. P_0(x \in C) = \alpha$$

Critical region  $C$  is most powerful (MP) among all tests of size  $\alpha$  or smaller  
fix  $\alpha$  then maximize power. Possible for LR evidence to disagree w/  
test result because hyp. test changes level of evidence to control  $\alpha$  as  $n \rightarrow \infty$

## Significance testing

use p-value as measure of evidence against  $H_0$ . (no alternatives, decisions  
between  $H_0$  &  $H_1$ , errors)

$$\text{p-value} = P(\text{data as or more extreme than observed} \mid H_0) = P(T(X) \geq T(\bar{x}) \mid H_0)$$

- for composite hypotheses apply N-P lemma to each pairing of ind. hypotheses  
if rejection decision rule is free of alternative hypothesis the test is  
uniformly most powerful Note: two-sided tests not UMP

Hypothesis tests are unbiased if  $P_{\theta_1}(\text{reject } H_0) \geq P_{\theta_0}(\text{reject } H_0) \quad \forall \theta_1 \neq \theta_0$   
 $\inf_{\theta \in \Theta_1} 1 - \beta(\theta) \geq \alpha$

Tests are consistent if for series  $\delta_1, \delta_2, \dots, \delta_n$   $1 - \beta_{\delta_n}(\theta_1) \rightarrow 1 \text{ as } n \rightarrow \infty$

Monotone Likelihood Ratio (MLR) family of pmfs or pdfs  $g(t|\theta)$  has MLR if  
 $\forall \theta_2 > \theta_1 \quad \frac{g(t|\theta_2)}{g(t|\theta_1)}$  is monotone function of  $t$

Any exponential family  $g(t|\theta) = h(t) c(\theta) \exp[w(\theta)t]$  has MLR if  $w(\theta)$  non-decreasing function

Karlin-Rubin Thm - Let  $T(X)$  be suff. stat for  $\theta$  and assume  $g(+|\theta)$  has MLE  
 For any  $t_0$  no test of  $H_0: \theta \leq \theta_0$  vs.  $H_1: \theta > \theta_0$  that rejects ~~rejects~~  $H_0$  when  
 $T(X) > t_0$  is UMP test of size  $\alpha = P_{\theta_0}(T(X) > t_0)$  (14)

Generalized Likelihood Ratio Test  $H_0: \theta \in \Theta_0$   $H_1: \theta \in \Theta_1$ ,  $\Theta_0 \cap \Theta_1 = \emptyset$

$$\delta(X) = \begin{cases} 1 & \lambda(X) \leq \lambda_0 \\ 0 & \text{o.w.} \end{cases}$$

$\lambda_0$  chosen s.t.  $\alpha = \sup_{\theta \in \Theta_0} P_\theta(\lambda(X) \leq \lambda_0)$  for

$$\lambda(X) = \frac{\sup_{\theta \in \Theta_0} f(x; \theta)}{\sup_{\theta \in \Theta_1} f(x; \theta)} = \frac{f(x; \hat{\theta}_0)}{f(x; \hat{\theta}_1)} = \frac{f(x; \hat{\theta}_0)}{f(x; \hat{\theta})}$$

$-2 \log \lambda(X) \xrightarrow{d} \chi^2_{d-d_0}$   $d = \dim \Theta$   $d_0 = \dim \Theta_0$  under some regularity conditions

Wald Test based on large sample distribution of parameter estimate  
 after MLE + asymptotic normality of MLE. for  $H_0: \theta = \theta_0$  v.  $H_1: \theta \neq \theta_0$

$$\frac{\hat{\theta} - \theta_0}{\sqrt{\text{Var}(\hat{\theta})}} \sim N(0, 1)$$

Wald Tests use estimated variance which is consistent under null or alternative

Score Test based on large sample behavior of score function under  $H_0$

$$S_n(\theta_0) = \frac{\partial \ell(\theta_0)}{\partial \theta} \quad \text{under } H_0 \quad E_{\theta_0}[S_n(\theta_0)] = 0 \quad \text{Var}[S_n(\theta_0)] = I(\theta_0)$$

$$\frac{S_n(\theta_0)}{\sqrt{I_n(\theta_0)}} \sim N(0, 1)$$

Score tests use variance under null. If  $H_0$  true good power, o.w. lose power

- GLRT, Wald, and Score are asymptotically equivalent under  $H_0$  but not under  $H_1$

- LRRTs invariant to transformations of parameter space

- Wald tests do not work well when parameter is near edge of param space

- Score tests are most powerful for small deviations from  $H_0$

## Multiple Testing

when multiple tests performed probability of falsely reject at least one increases with additional tests

one solution is to redefine level of significance based on number of tests

$$FWER = P_0(\text{reject at least one } H_0 \text{ falsely}) = 1 - P_0(\text{accept all } H_0) = 1 - (1-\alpha)^m$$

for  $m$  tests with  $H_0^i \vee H_1^i$  size  $\alpha_i = \alpha$   $\sum \alpha_i = m\alpha$

Bonferroni correction (very conservative)

compare to  $\alpha_{adj} = \alpha/m$  or compare  $p_{adj} = m p_i$  to  $\alpha$

## - False Discovery Rate

$FDR \approx E[\frac{\text{prop of incorrect rejections}}{\text{prop of rejections}}] = P(H_1^i | H_0^i \text{ rejected})$  empirical Bayes type estimate  
controlling FDR does not control Type I or Type II errors

## - Benjamini-Hochberg method control FDR at level $\gamma$

find largest  $i$  such that  $p_{(i)} \leq \frac{i\gamma}{m}$  where  $i$  is rank of p-value  
reject all p-values w/ smaller rank (some more subtle nuances)

can only control one of per-comparison error rate, FWER or FDR at a time

## Bootstrap - nsc estimate of s.e./CI for sampling dist when analytical solution

complex or distribution-free approx is desired

$$X_1, \dots, X_n \sim F(X) \quad T_n = g(\underline{X})$$

$$V_F(T_n) \approx \hat{V}_F(T_n) \approx V_{boot}$$

1. Estimate  $V_F(T_n)$  with  $\hat{V}_F(T_n)$

2. Approximate  $\hat{V}_F(T_n)$  using simulation (resampling)

### simulation

1. draw resamples of size  $n$  from  $\hat{F}(X)$   $X_1^*, \dots, X_n^* \sim \hat{F}(X)$

2. calculate  $T_n^* = g(\underline{X}^*)$

3. Repeat 1+2  $B$  times

4. Use  $T_{n,1}^*, \dots, T_{n,B}^*$  to estimate dist. of  $T_n$

Bootstrap is asymptotic &  $\hat{F}(X)$  must be representative of  $F(X)$

Can use double bootstrap to check variance of  $V_{boot}$  itself

### common intervals

1. Normal  $\hat{\theta} \pm Z_{\alpha/2} \sqrt{V_{boot}}$

2. Percentile  $(\hat{\theta}_{1-\alpha/2}^*, \hat{\theta}_{\alpha/2}^*)$

3. Pivotal  $(2\hat{\theta} - \hat{\theta}_{1-\alpha/2}^*, 2\hat{\theta} - \hat{\theta}_{\alpha/2}^*)$

4. Bias-corrected